# Introduction: The Interplay of Symmetric Tensors and Neural Networks

Speaker: Maksym Zubkov, University of British Columbia Venue: Informal Reading Group on Classical Algebraic Geometry Date: September 9th, 2025

Field: Applied algebraic geometry

**Key Results**: Defining and establishing the connection between homogeneous polynomial and symmetric tensors. Discussing their application to algebraic neural networks.

#### 1. Homogeneous polynomials

One of the main objects of our study will be homogeneous polynomials and symmetric tensors. We begin by defining homogeneous polynomials.

Let F be a field of characteristic zero. For the remainder of this reading group, we will work mostly over the complex numbers  $\mathbb{C}$  (or over the reals  $\mathbb{R}$ , when specified).

**Definition 1.1** A homogeneous polynomial of degree r over a field F is a polynomial in which every monomial has degree r.

**Example 1.1** Let  $F = \mathbb{C}$  and  $f \in \mathbb{C}[x, y, z]$ . Then

$$f(x, y, z) = x^3 + y^3 + z^3 + 6xyz$$

is a homogeneous polynomial of degree r=3.

**Remark 1.1** The space of all homogeneous polynomials of degree r in n variables with coefficients in F will be denoted by  $S^r(F^n)$ .

**Exercise 1.1** What is the dimension of  $S^r(F^n)$  as a vector space over F?

#### 2. Symmetric tensors

Our next object of study is a symmetric tensor of order r over an n-dimensional vector space. Before introducing symmetric tensor, let us first define a general tensor.

We think of a general tensor as a multiarray, i.e., as an element of the space

$$T \in F^{d_1 \times d_2 \times \dots \times d_r}$$

where r is called the *order* of the tensor and each  $d_i$  is a positive integer. Equivalently, we may write

$$T = (a_{i_1 \dots i_r}),$$

where  $T(i_1, \ldots, i_r) = a_{i_1 \ldots i_r}$  are its entries.

**Example 2.1** Let  $T \in F^{2 \times 2 \times 2}$ . Then T is a tensor of order 3 whose entries may be displayed as two  $2 \times 2$  matrices:

$$T = \left\{ \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} \right\}.$$

This is a somewhat rudimentary definition, but it will suffice for our purposes.

## 2.1 Definition of a symmetric tensor

Let  $\mathfrak{S}_r$  denote the symmetric group on r elements. We now define symmetric tensors.

**Definition 2.1 (Symmetric tensor)** A tensor T of order r is called symmetric if it is invariant under any permutation of its indices. That is, for every multi-index  $(i_1, \ldots, i_r)$  and every  $\sigma \in \mathfrak{S}_r$ ,

$$T(i_1,\ldots,i_r) = T(i_{\sigma(1)},\ldots,i_{\sigma(r)}).$$

**Example 2.2** Let  $T \in F^{2 \times 2 \times 2}$ . One example of a symmetric tensor of order 3 is the  $2 \times 2 \times 2$  array with entries

$$T = \left\{ \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}, \begin{bmatrix} 2 & 3 \\ 3 & 4 \end{bmatrix} \right\}.$$

**Remark 2.1** The space of all symmetric tensors of order r on  $F^n$  is denoted by  $Sym_r(F^n)$ .

## 3. The connection between homogneous polynomials and symmetric tensors

Next, we want to construct the maps

$$L: S^{r}(F^{n}) \to Sym^{r}(F^{n}),$$
  

$$R: Sym^{r}(F^{n}) \to S^{r}(F^{n}).$$
(1)

## 3.1 The L map

Let  $\partial_{x_i}: F[x_1,\ldots,x_n] \to F[x_1,\ldots,x_n]$  denote the formal partial derivative

$$\partial_{x_i}(f) = \frac{\partial f}{\partial x_i}.$$

If  $f \in S^r(F^n)$ , we may write

$$f(\mathbf{x}) = \sum_{|I|=r} a_I \mathbf{x}^I,$$

where  $I = (i_1, i_2, \dots, i_n)$  is a multi-index,  $a_I = a_{i_1 i_2 \dots i_n}$ , and  $\mathbf{x}^I = x_1^{i_1} x_2^{i_2} \dots x_n^{i_n}$ . For a multi-index  $I = (i_1, \dots, i_n)$ , define the differential operator

$$\partial_{\mathbf{x}^I} = (\partial_{x_1})^{i_1} \circ \cdots \circ (\partial_{x_n})^{i_n}.$$

Then the map L associates to f the symmetric tensor  $T_f$  of order r defined by

$$T_f(i_1,\ldots,i_n) = \partial_{\mathbf{x}^I}(f).$$

**Example 3.1** Let  $f \in S^2(\mathbb{C}^3)$  be given by

$$f(x, y, z) = ax^2 + by^2 + cz^2 + Axy + Bxz + Cyz.$$

Then

$$L(f) = \begin{bmatrix} 2a & A & B \\ A & 2b & C \\ B & C & 2c \end{bmatrix}.$$

## 3.2 The R map

Now, given a symmetric tensor T, we want to produce a homogeneous polynomial.

$$R(T) = f_T$$

where

$$f_T(\mathbf{x}) = \sum_{|I|=r} \frac{1}{\binom{n}{i_1, i_2, \dots, i_n}} T(i_1, \dots, i_n) \mathbf{x}^I.$$

**Exercise 3.1** If F is a field of characteristic zero, then the maps L and R establish a one-to-one correspondence between the space of homogeneous polynomials  $S^r(F^n)$  and the space of symmetric tensors  $Sym^r(F^n)$ .

## 4. Rank one symmetric tensors

Let V be a vector space over F, and  $V^*$  its dual vector space, i.e.

$$V^* = \{\alpha : V \to F \mid \alpha \text{ is a linear functional}\}.$$

A simple tensor  $\alpha \otimes v \in V^* \otimes V$  defines a rank-one linear map  $V \to V$  by  $x \mapsto \alpha(x) v$ .

**Definition 4.1** The tensor  $\alpha \otimes v \in V^* \otimes V$  is called rank one if its corresponding linear map

$$T_{\alpha,v}: V \to V, \quad T_{\alpha,v}(x) = \alpha(x) v$$

is rank one.

**Example 4.1** Let  $V = \mathbb{C}^2$  with basis  $e_1, e_2$  and dual basis  $e^1, e^2$ . If  $A \in F^{2 \times 2}$  with

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix},$$

then the associated tensor in  $V^* \otimes V$  is

$$\widetilde{A} = a_{11} e^1 \otimes e_1 + a_{12} e^1 \otimes e_2 + a_{21} e^2 \otimes e_1 + a_{22} e^2 \otimes e_2.$$

In coordinates, if  $v, w \in V$ , then the rank-one tensor can be written as the outer product

$$v \otimes w = v^T w,$$

where v, w are row vectors.

# Example 4.2 If

$$a = \begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix},$$

then

$$a \otimes a = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} = \begin{bmatrix} a_1^2 & a_1 a_2 & a_1 a_3 \\ a_1 a_2 & a_2^2 & a_2 a_3 \\ a_1 a_3 & a_2 a_3 & a_3^2 \end{bmatrix}.$$

**Definition 4.2** If  $v_1, \ldots, v_n \in V$  have coordinates  $v_{ij}$  (where i indexes the vector  $v_i$  and j indexes the jth coordinate), then their tensor (outer) product is defined by

$$v_1 \otimes v_2 \otimes \cdots \otimes v_n = (v_{1i_1} v_{2i_2} \cdots v_{ni_n}),$$

where the entry at  $(i_1, \ldots, i_n)$  is the product of the corresponding coordinates.

# 4.1 Homogeneous polynomials and Veronese map

**Exercise 4.1** If  $a = \begin{bmatrix} a_1 & a_2 & \dots & a_n \end{bmatrix}$ , then

$$R(a \otimes \cdots \otimes a) = (a_1x_1 + \cdots + a_nx_n)^r$$
.

In other words, we have a map  $\mathcal{V}_r: V \to S^r(F^n)$  given by

$$\mathcal{V}_r(a) = (a_1 x_1 + \dots + a_n x_n)^r,$$

which is called the Veronese map.

**Exercise 4.2** When r = 2, show that the image of  $V_2$  is the set of symmetric matrices of rank one, i.e., the variety defined by the vanishing of all  $2 \times 2$  minors.

#### 5. Symmetric Rank

In other words, the Veronese map parametrizes all symmetric rank-one tensors. What is a tensor of rank m?

**Definition 5.1** A symmetric tensor T has symmetric rank m if it can be written minimally as a linear combination of m symmetric rank-one tensors, i.e.,

$$T = v_1^{\otimes r} + v_2^{\otimes r} + \dots + v_m^{\otimes r},$$

where each  $v_i \in V$ , and no such expression exists with fewer than m terms. We write

$$rank_S(T) = m$$
.

Example 5.1 If

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix},$$

then

$$A = \frac{1}{2} \Big( (e_1 + e_2) \otimes (e_1 + e_2) - (e_1 - e_2) \otimes (e_1 - e_2) \Big).$$

**Exercise 5.1** Show that  $rank_S(A) = 2$ .

#### 5.1 Waring Rank

On the level of homogeneous forms, the symmetric rank is called the Waring rank. In other words, a form  $f \in S^r(F^n)$  has Waring rank m if there exist m nonzero linear forms  $l_1, \ldots, l_m$  such that

$$f = l_1^r + \dots + l_m^r.$$

Example 5.2 If f(x,y) = 2xy, then

$$f(x,y) = (x+y)^2 - (x-y)^2.$$

# 6. Algebraic Shallow Neural Networks

Let  $\mathbf{d} = (n, m, k)$  be a tuple of positive integers. Consider a map  $f_{\mathbf{w}} : F^n \to F^k$  defined by

$$f_{\mathbf{w}}(\mathbf{x}) = W_2 \sigma(W_1 \mathbf{x}),$$

where  $W_1 \in F^{m \times n}$ ,  $W_2 \in F^{k \times m}$ , and  $\sigma$  is an algebraic activation function (polynomial, rational, or ReLU) applied componentwise.

# 6.1 Polynomial activation

If  $\sigma(x) = x^r$ , then  $f_{\mathbf{w}} \in (S^r(F^n))^k$ .

**Example 6.1** Let  $\mathbf{d} = (2, 2, 1)$  and r = 2. Then the output of the network is

$$f_{\mathbf{w}}(\mathbf{x}) = \begin{bmatrix} b_1 & b_2 \end{bmatrix} \sigma \begin{pmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \end{pmatrix}.$$

Writing  $\ell_1 = a_{11}x_1 + a_{12}x_2$  and  $\ell_2 = a_{21}x_1 + a_{22}x_2$ , this becomes

$$f_{\mathbf{w}}(\mathbf{x}) = \begin{bmatrix} b_1 & b_2 \end{bmatrix} \begin{bmatrix} \ell_1^2 \\ \ell_2^2 \end{bmatrix} = b_1 \ell_1^2 + b_2 \ell_2^2.$$

Expanding, we obtain

$$f_{\mathbf{w}}(\mathbf{x}) = (b_1 a_{11}^2 + b_2 a_{21}^2) x_1^2 + (2b_1 a_{11} a_{12} + 2b_2 a_{21} a_{22}) x_1 x_2 + (b_1 a_{12}^2 + b_2 a_{22}^2) x_2^2.$$